

A Note On Double-Null Form For Space-Times Metrics Having (2 + 1) And (3 + 1) Dimensions

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ABSTRACT

In this research article, (2 + 1) dimension space-times are categorized, depending on the probability of transforming into a double-null form. Results originate that those classes of (2 + 1)-dimensional space-times that have non-zero co-efficients, g_{02} or g_{12} , are unable to transform to a desirable form. Further, it is also confirmed that a class of (3 + 1)-dimensional space-times possessing non-zero coefficients, g_{02} or g_{12} , cannot be transformed to a double-null form.

Keywords— Double-Null Form, Coordinate Transformation, Space-Time Metrics.

1 INTRODUCTION

A variety of different forms of space-time metrics are cast off in, solar-terrestrial relationships, exploration of black hole (BH) space-times, Numerical Relativity and Newman-Penrose formalism etc. The necessity for other forms stand up from the datum that often numerous physical procedures are more implicit, data under investigation is well-organized or calculations with more ease, in a particular form than in another one. In literature of relativity, a double-null (DN) form in (2 + 1) dimensional space-times has a form:

$$ds^2 = 2g du dv + g d\phi^2, \quad (1) \quad \text{where } u, v, \phi \text{ are functions of } u, v \text{ and } \phi.$$

where $g_{00}, g_{01}, g_{02}, g_{11}, g_{12}, g_{22}$ are functions of u, v and ϕ .

It is extensively utilized by Howard in exploring BH space-times [1] and by Roman in their prior work [2]. It is also supportive in Newman-Penrose formalism [3]–[6]. In the study of vacuum space-times, the Newman-Penrose formalism makes things easier in DN form, that permits

straightforward proof of numerous theorems.

In Numerical Relativity, DN form play a major role that applied to various zones, for instance in perturbed BH's, cosmological models, and neutron stars [7]–[9]. In numerical analysis, vigilant courtesy is considered for the stability and convergence of numerical solutions and is possible only with DN form. Apart from Numerical Relativity and Newman-Penrose formalism, it has been useful in formulation of light-cone gauge of string theory, that is a remarkable effort to unite quantum physics with relativity [10]–[14].

The plan for the research paper is, in sections two and three, it is focused on the existence of DN form for different classes of (2 + 1) and (3 + 1) dimensional space-times. Where as Section 4, is reserved for conclusion and discussion.

2 EXISTENCE OF DOUBLE-NUL FORM FOR (2+1) DI-MENSIONAL SPACE-TIMES

The (2 + 1) dimensional space-time is expressed as metric as

$$ds^2 = g_{00}dt^2 + g_{11}dr^2 + g_{22}d\phi^2 + 2g_{01}dtdr + 2g_{02}dtd\phi + 2g_{12}drd\phi, \quad (2)$$

here g_{00} , g_{11} , g_{22} , g_{01} , g_{02} and g_{12} are function of t , r and ϕ .

For transformation of a metric (2) to a desired form (1), let t and r be a function of $u^{\hat{}}$, $v^{\hat{}}$ and utilizing transformation of coordinates:

$$g_{\tilde{a}\tilde{b}} = \frac{\partial x^p}{\partial x^{\tilde{a}}} \frac{\partial x^q}{\partial x^{\tilde{b}}} g_{lm}, \quad (3)$$

where x^p , x^q and $x^{\tilde{a}}$, $x^{\tilde{b}}$ corresponds to the (t, r, ϕ) and $(u^{\hat{}}, v^{\hat{}}, \phi)$ coordinates respectively, with $p, q, \tilde{a}, \tilde{b} = 0, 1, 2$, to get the partial differential equations (PDE) system as

$$g_{\tilde{0}\tilde{0}} = \left(\frac{\partial t}{\partial u^{\hat{}}} \right)^2 g_{00} + 2 \left(\frac{\partial t}{\partial u^{\hat{}}} \right) \left(\frac{\partial r}{\partial u^{\hat{}}} \right) g_{01} + \left(\frac{\partial r}{\partial u^{\hat{}}} \right)^2 g_{11}, \quad (4)$$

$$g_{\tilde{0}\tilde{1}} = \frac{\partial t}{\partial u^{\hat{}}} \frac{\partial t}{\partial v^{\hat{}}} g_{00} + \left(\frac{\partial t}{\partial u^{\hat{}}} \frac{\partial r}{\partial v^{\hat{}}} + \frac{\partial r}{\partial u^{\hat{}}} \frac{\partial t}{\partial v^{\hat{}}} \right) g_{01} + \frac{\partial r}{\partial u^{\hat{}}} \frac{\partial r}{\partial v^{\hat{}}} g_{11},$$

$$g_{\tilde{1}\tilde{1}} = \left(\frac{\partial r}{\partial v^{\hat{}}} \right)^2 g_{00} + 2 \left(\frac{\partial r}{\partial v^{\hat{}}} \right) \left(\frac{\partial r}{\partial v^{\hat{}}} \right) g_{01} + \left(\frac{\partial r}{\partial v^{\hat{}}} \right)^2 g_{11}, \quad (5)$$

$$g_{\tilde{1}\tilde{2}} = \frac{\partial r}{\partial v^{\hat{}}} \frac{\partial t}{\partial v^{\hat{}}} g_{00} + \left(\frac{\partial r}{\partial v^{\hat{}}} \frac{\partial r}{\partial v^{\hat{}}} + \frac{\partial t}{\partial v^{\hat{}}} \frac{\partial r}{\partial v^{\hat{}}} \right) g_{01} + \frac{\partial r}{\partial v^{\hat{}}} \frac{\partial r}{\partial v^{\hat{}}} g_{11},$$

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$$g_2^2 = g_{22}, \quad (6)$$

$$g_{01} = \left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial t}{\partial v} \right) g_{00} + \left(\frac{\partial r}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) g_{11} + \left(\frac{\partial t}{\partial u} \frac{\partial r}{\partial v} + \frac{\partial r}{\partial u} \frac{\partial t}{\partial v} \right) g_{01}, \quad (7)$$

$$g_{02} = \left(\frac{\partial t}{\partial u} \right) \frac{g_{02}}{g_{02}} + \left(\frac{\partial r}{\partial u} \right) \frac{g_{12}}{g_{12}}, \quad (8)$$

$$g_{12} = \left(\frac{\partial t}{\partial v} \right) \frac{g_{02}}{g_{02}} + \left(\frac{\partial r}{\partial v} \right) \frac{g_{12}}{g_{12}}. \quad (9)$$

With the required condition: $g_{00} = g_{11} = g_{22} = 0$, the above set of PDE's from (4) to (9) condense as

$$\left(\frac{\partial t}{\partial u} \right)^2 g_{00} + \left(\frac{\partial r}{\partial u} \right)^2 g_{11} + 2 \left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial r}{\partial u} \right) g_{01} = 0, \quad (10)$$

$$\left(\frac{\partial t}{\partial v} \right)^2 g_{00} + \left(\frac{\partial r}{\partial v} \right)^2 g_{11} + 2 \left(\frac{\partial t}{\partial v} \right) \left(\frac{\partial r}{\partial v} \right) g_{01} = 0, \quad (11)$$

$$g_{22} = g_{22}, \quad (12)$$

$$\left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial t}{\partial v} \right) g_{00} + \left(\frac{\partial r}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) g_{11} + \left(\frac{\partial t}{\partial u} \frac{\partial r}{\partial v} + \frac{\partial r}{\partial u} \frac{\partial t}{\partial v} \right) g_{01} = g_{01}, \quad (13)$$

$$\frac{\partial t}{\partial u} \frac{g_{02}}{g_{02}} + \left(\frac{\partial t}{\partial u} \right) g_{02} + \frac{\partial r}{\partial u} \frac{g_{12}}{g_{12}} + \left(\frac{\partial r}{\partial u} \right) g_{12}$$

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$$+ \left(\frac{\partial r}{\partial t} \right) g = 0, \quad (14)$$

$$= 0. \quad (15)$$

$$\partial v^{\hat{}}_{02} \quad \partial v^{\hat{}}_{12}$$

The desired Jacobian is,

$$J = \left(\frac{\partial t}{\partial v^{\hat{}}} \right) \left(\frac{\partial r}{\partial v^{\hat{}}} \right) - \left(\frac{\partial t}{\partial v^{\hat{}}} \right) \left(\frac{\partial r}{\partial u^{\hat{}}} \right), \quad (16)$$

for a non-zero transformation (3), Eq.(14) and (15) possess only trivial solution $g_{02} = g_{12} = 0$

. It reflects that if a metric (2) comprises g_{02} or g_{12} then it could not be transformed to the desired DN form (1). Thus, the utmost general form for the (2 + 1) dimensional space-time metric that can be transformed to a DN form is

$$ds^2 = g_{00}dt^2 + g_{11}dr^2 + g_{22}d\phi^2 + 2g_{01}dtdr. \quad (17)$$

In order to obtain specific transformations to transform metric (17) in double null form, we consider the following cases:

(a) $g_{00}, g_{11}, g_{22} \neq 0$ and $g_{01} = 0$

(d) $g_{00}, g_{22}, g_{01} \neq 0$ and $g_{11} = 0$

(c) $g_{11}, g_{22}, g_{01} \neq 0$ and $g_{00} = 0$

(d) $g_{00}, g_{11}, g_{22}, g_{01} \neq 0$.

2.1 Case a: $g_{00}, g_{11}, g_{22} \neq 0$ and $g_{01} = 0$

The above set of Eqs.(10) to (13) becomes

$(\frac{\partial t}{\partial u})^2$

$$\frac{\partial u}{\partial v} = \frac{g_{00}}{g_{11}} \left(\frac{\partial r}{\partial u} \right)^2 + \left(\frac{\partial r}{\partial v} \right)^2 \quad g_{11} = 0, (18)$$

$$\frac{\partial u}{\partial v} = \frac{g_{00}}{g_{11}} + \left(\frac{\partial r}{\partial v} \right)^2 \quad g_{11} = 0, (19)$$

$$g_{22} = g, \quad (20)$$

$$\left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial t}{\partial v} \right) g + \left(\frac{\partial r}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) g = g \quad (21)$$

With the requirement of non-zero Jacobian (16), Eqs.(18) and (19) implies

$$\left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) + \left(\frac{\partial t}{\partial v} \right) \left(\frac{\partial r}{\partial u} \right) = 0. (22)$$

$$\frac{\partial u}{\partial v} \frac{\partial v}{\partial u} + \frac{\partial v}{\partial u} \frac{\partial u}{\partial v} = 0$$

Which results in the transformations of

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$$t = \Phi(u^{\wedge} \pm v^{\wedge}), r = \Psi(u^{\wedge} \mp v^{\wedge}), (23)$$

with Φ and Ψ as arbitrary functions.

2.2 Case b: $g_{00}, g_{22}, g_{01} \neq 0$ and $g_{11} = 0$

While considering the case b, the above system from Eqs.(10) to (13) becomes as

$$\left(\frac{\partial}{\partial t} \right)^2 \left(\frac{\partial}{\partial t} \right) \left(\frac{\partial}{\partial r} \right) \frac{\partial u}{\partial u} g_{00} + 2 \frac{\partial u}{\partial u} \frac{\partial u}{\partial u} g_{01} = 0, (24)$$

$$\left(\frac{\partial}{\partial t} \right)^2 \left(\frac{\partial}{\partial t} \right) \left(\frac{\partial}{\partial r} \right) \frac{\partial v}{\partial v} g_{00} + 2 \frac{\partial v}{\partial v} \frac{\partial v}{\partial v} g_{01} = 0, (25)$$

$$g_{22} = g, \quad (26)$$

$$\left(\frac{\partial}{\partial t} \right) \left(\frac{\partial}{\partial t} \right) g + \left(\frac{\partial}{\partial t} \frac{\partial r}{\partial u} + \frac{\partial r}{\partial u} \frac{\partial t}{\partial v} \right) g_{01} = g_{01}. \quad (27)$$

Eqs.(24) and (25) can be expressed as

$$\frac{\partial}{\partial t} \left(\frac{\partial}{\partial t} g \right) + \frac{\partial r}{\partial u} \left(\frac{\partial}{\partial t} g \right) = 0 \quad (28)$$

$$\frac{\partial u}{\partial u} \frac{\partial u}{\partial u} g_{00} + \frac{\partial u}{\partial u} \frac{\partial u}{\partial u} g_{01}$$

and

$$\frac{\partial}{\partial t} \left(\frac{\partial}{\partial t} g \right) + \frac{\partial r}{\partial u} \left(\frac{\partial}{\partial t} g \right) = 0. \quad (29)$$

$$\frac{\partial v}{\partial v} \frac{\partial v}{\partial v} g_{00} + \frac{\partial v}{\partial v} \frac{\partial v}{\partial v} g_{01}$$

Eqs.(28) and (29) are satisfied by the cases:

$$(b1) \frac{\partial}{\partial t} \frac{\partial}{\partial r} = \frac{\partial}{\partial v} \frac{\partial}{\partial u}$$

$$(b2) \frac{\partial}{\partial u} \frac{\partial}{\partial u} g_{00} + 2 \frac{\partial}{\partial u} \frac{\partial}{\partial v} g_{01} = \frac{\partial}{\partial t} g_{00} + 2 \frac{\partial}{\partial r} g_{01} = 0$$

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$$(b3) \frac{\partial t}{\partial u} = \frac{\partial t}{\partial v} g_{00} + 2 \frac{\partial r}{\partial v} g_{01} = 0$$

$$(b4) \frac{\partial t}{\partial v} = \frac{\partial t}{\partial u} g_{00} + 2 \frac{\partial r}{\partial u} g_{01} = 0.$$

It is observed that in cases (b1) and (b2), the required DN form does not exist as it lead to contradictions $0 = 0$ and $g_{00} = 0$. Anyhow, required DN form exist for the 2 cases, (b3) and (b4).

2.3 Case c: $g_{11}, g_{22}, g_{01} \neq 0$ and $g_{00} = 0$

In case c, the system of Eqs.(10) to (13) compiles to

$$\frac{\partial u}{\partial r} g_{11} + 2 \frac{\partial u}{\partial t} g_{01} = 0, (30)$$

$$\frac{\partial v}{\partial r} g_{11} + 2 \frac{\partial v}{\partial t} g_{01} = 0, (31)$$

$$g_{22} = g, \quad (32)$$

$$\left(\frac{\partial r}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) g + \left(\frac{\partial t}{\partial u} \frac{\partial r}{\partial v} + \frac{\partial r}{\partial u} \frac{\partial t}{\partial v} \right) g_{01} = g. \quad (33)$$

Eqs.(29) and (30) can be expressed as

$$\frac{\partial r}{\partial u} \left(\frac{\partial r}{\partial v} g + \frac{\partial t}{\partial v} g_{01} \right) = 0 \quad (34)$$

$$\frac{\partial u}{\partial r} g_{11} + 2 \frac{\partial u}{\partial t} g_{01} = 0$$

and

$$\frac{\partial r}{\partial u} \left(\frac{\partial g}{\partial t} + \frac{\partial}{\partial u} \right) = 0. \quad (35)$$

g

$$\frac{\partial v}{\partial u} \quad \frac{\partial v}{\partial u}^{11}$$

$$\frac{\partial v}{\partial v}^{01}$$

Eqs.(34) and (35), satisfied the following cases: (c1) $\frac{\partial r}{\partial u} = \frac{\partial r}{\partial v} = 0$

$$\frac{\partial u}{\partial u} \quad \frac{\partial v}{\partial v}$$

$$(c2) \quad \frac{\partial r}{\partial u} g_{11} + 2 \frac{\partial r}{\partial u} \frac{\partial g}{\partial v} = \frac{\partial r}{\partial v} g_{11} + 2 \frac{\partial r}{\partial v} \frac{\partial g}{\partial u} = 0$$

$$(c3) \quad \frac{\partial r}{\partial u} = \frac{\partial r}{\partial v} g_{11} + 2 \frac{\partial r}{\partial v} \frac{\partial g}{\partial v} = 0$$

$$(c4) \quad \frac{\partial r}{\partial v} = \frac{\partial r}{\partial u} g_{11} + 2 \frac{\partial r}{\partial u} \frac{\partial g}{\partial u} = 0.$$

Cases (c1) and (c2), again lead to contradictions $g_{00} = 0$ and $g_{11} = 0$ respectively, anyhow, the form exist for the cases (c3) and (c4).

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2.4 Case d: $g_{00}, g_{11}, g_{22}, g_{01} \neq 0$

In considering case d, the above system of Eqs.(10) to (13) compiles as

$$\left(\frac{\partial}{\partial t} \right)^2 \quad \left(\frac{\partial r}{\partial t} \right)^2 \quad \left(\frac{\partial t}{\partial t} \right) \left(\frac{\partial r}{\partial r} \right)$$

$$\frac{\partial u}{\partial u} \quad g_{00} + \frac{\partial u}{\partial u} g_{11} + 2 \frac{\partial u}{\partial u} \frac{\partial}{\partial u} g_{01} = 0, (36)$$

$$\left(\frac{\partial}{\partial t} \right)^2 \quad \left(\frac{\partial r}{\partial r} \right)^2 \quad \left(\frac{\partial t}{\partial t} \right) \left(\frac{\partial r}{\partial r} \right)$$

$$\frac{\partial v}{\partial v} \quad g_{00} + \frac{\partial v}{\partial v} g_{11} + 2 \frac{\partial v}{\partial v} \frac{\partial}{\partial v} g_{01} = 0, (37)$$

$$g_{22} = g_{22} \quad \left(\frac{\partial t}{\partial t} \right) \left(\frac{\partial t}{\partial t} \right) g_{00} + \left(\frac{\partial r}{\partial r} \right) \left(\frac{\partial r}{\partial r} \right) g_{11} + \left(\frac{\partial t}{\partial t} \frac{\partial r}{\partial r} + \frac{\partial r}{\partial t} \frac{\partial t}{\partial t} \right) g_{01} = g_{01}$$

$$\frac{\partial u}{\partial t} + \frac{\partial v}{\partial x} = -\frac{g}{f} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) \quad (39)$$

Requiring the Jacobian (16) to be non-zero, Eqs.(36) and (37) imply

$$\frac{\partial u}{\partial t} \frac{\partial v}{\partial t} g - \frac{\partial u}{\partial r} \frac{\partial v}{\partial r} g = 0, \quad (40)$$

$$(\frac{\partial t}{\partial r} \frac{\partial r}{\partial t} + \frac{\partial t}{\partial t} \frac{\partial r}{\partial r}) g + 2 (\frac{\partial t}{\partial t}) (\frac{\partial t}{\partial t}) g = 0, \quad (41)$$

$$(\underline{\partial t} \underline{\partial r} + \underline{\partial r} \underline{\partial t}) g + 2 (\underline{\partial r}) (\underline{\partial r}) g = 0. \quad (42)$$

The above system of Eqs.(40) to (42) have non-trivial solutions if

$$(\frac{\partial t}{\partial t} \frac{\partial r}{\partial r} + \frac{\partial t}{\partial t} \frac{\partial r}{\partial r}) = 0, \quad (43)$$

which results in transformations:

$t = \Phi(u^\wedge \pm v^\wedge)$, $r = \Psi(u^\wedge \mp v^\wedge)$, (44) where Φ and Ψ are arbitrary functions.

3 DOUBLE-NULL FORM FOR (3+1) DIMENSIONAL SPACE-TIMES

Consider the general four dimensional space-time metric:

$$ds^2 = g_{00}dt^2 + g_{11}dr^2 + g_{22}d\theta^2 + g_{33}d\phi^2 + 2g_{01}dtdr + 2g_{02}dtd\theta + 2g_{03}dtd\phi + 2g_{12}drd\theta + 2g_{13}drd\phi + 2g_{23}d\theta d\phi, \quad (45)$$

where $g_{00}, g_{11}, g_{22}, g_{33}, g_{01}, g_{02}, g_{03}, g_{12}, g_{13}$ and g_{23} are functions of t, r, θ and ϕ .

For the purpose of transformation of metric (45) to a desired DN form (1), take t and r to be

function of $(\hat{u}, \hat{v})$ and utilize again the transformation,

$$a \tilde{b} \quad g =_p \frac{\partial x}{\partial x^q} \tilde{a} \frac{\partial x^q}{\partial x^b}.$$

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$g_{lm},$ (46)

where x^p, x^q and x^a, x^b refer to the (t, r, θ, ϕ) and $(\hat{u}, \hat{v}, \theta, \phi)$ coordinates respectively, with $p, q, a, b = 0, 1, 2, 3$, and also requiring $g_{00} = g_{11} = g_{22} = g_{02} = g_{03} = g_{12} = g_{13} = g_{23} = 0$, to get the

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(38)

system of PDE's as:

$$\left(\frac{\partial}{\partial t}\right)^2 \left(\frac{\partial}{\partial r}\right)^2 \left(\frac{\partial}{\partial t}\right) \left(\frac{\partial}{\partial r}\right) \hat{u} = g_{00} + \frac{\partial \hat{u}}{\partial r} g_{11} + 2 \frac{\partial \hat{u}}{\partial t} g_{01} = 0, (47)$$

$$\left(\frac{\partial}{\partial t}\right)^2 \left(\frac{\partial}{\partial r}\right)^2 \left(\frac{\partial}{\partial t}\right) \left(\frac{\partial}{\partial r}\right) \hat{v} = g_{00} + \frac{\partial \hat{v}}{\partial r} g_{11} + 2 \frac{\partial \hat{v}}{\partial t} g_{01} = 0, (48)$$

$$g_{22} = 0, (49)$$

$$g_{33} = g_{\tilde{3}\tilde{3}} \quad (50)$$

$$\left(\frac{\partial}{\partial t}\right) \left(\frac{\partial}{\partial t}\right) g_{\hat{u}\hat{v}} + \left(\frac{\partial}{\partial r}\right) \left(\frac{\partial}{\partial r}\right) g_{\hat{u}\hat{v}} + \left(\frac{\partial}{\partial t} \frac{\partial}{\partial r} + \frac{\partial}{\partial r} \frac{\partial}{\partial t}\right) g_{\hat{u}\hat{v}} = g_{\hat{u}\hat{v}}^{00} + g_{\hat{u}\hat{v}}^{01}, \quad (51)$$

$$\frac{\partial}{\partial \hat{u}} \left(\frac{\partial}{\partial t}\right) g_{02} + \left(\frac{\partial}{\partial r}\right) g_{12} = 0, \quad (52)$$

$$\left(\frac{\partial}{\partial t}\right) g_{02} + \left(\frac{\partial}{\partial r}\right) g_{12} = 0. \quad (53)$$

$$\frac{\partial}{\partial \hat{v}} g_{02} + \frac{\partial}{\partial \hat{v}} g_{12} = 0$$

$$\frac{\partial}{\partial \hat{u}} \left(\frac{\partial}{\partial t}\right) g_{03} + \left(\frac{\partial}{\partial r}\right) g_{13} = 0, \quad (54)$$

$$\left(\frac{\partial}{\partial t}\right) g_{03} + \left(\frac{\partial}{\partial r}\right) g_{13} = 0. \quad (55)$$

$$\frac{\partial}{\partial \hat{v}} g_{03} + \frac{\partial}{\partial \hat{v}} g_{13} = 0$$

$$g_{23} = 0, (56)$$

Requiring the Jacobian to be:

$$J = \left(\frac{\partial t}{\partial u} \right) \left(\frac{\partial r}{\partial v} \right) - \left(\frac{\partial t}{\partial v} \right) \left(\frac{\partial r}{\partial u} \right) \quad (57)$$

of the transformation (46) to be non-zero, Eqs. (52) to (56), have only trivial solution

$$g_{02} = g_{12} = g_{13} = g_{03} = g_{23} = 0$$

. It predicts that if the metric (45) have g_{02} or g_{12} then it is not possible to transformed into the desired form (1).

4 CONCLUSION

Utilizing coordinate transformations, DN form for distinct space-times metrics in $(2 + 1)$ and $(3 + 1)$ dimensions have been formed. For that, it is presented the existence of DN form for different classes of general space-times metric in $(2 + 1)$ dimensions and is observed that required DN form existence depends only on two coefficients g_{02} and g_{12} of the metric. A class of $(2 + 1)$ dimensional space-time possessing non-zero coefficients g_{02} or g_{12} , it is not possible to transformed to the desired form. For the remaining classes, further investigation showed that a class in which $g_{00}, g_{11}, g_{22} \neq 0$ and $g_{01} = 0$ can be transformed into the required DN form. However, a class in

$$\text{which } g_{00}, g_{22}, g_{01} \neq 0 \text{ and } g_{11} = 0, \text{ having } \frac{\partial t}{\partial v} = \frac{\partial r}{\partial u} = 0 \text{ or } \frac{\partial t}{\partial v} g_{00} + 2 \frac{\partial r}{\partial u} g_{01} = \frac{\partial t}{\partial v} g_{00} + 2 \frac{\partial r}{\partial v} g_{01} = 0$$

cannot be transformed to DN form. Similar situation arises in a class which has $g_{11}, g_{22}, g_{01} \neq 0$ and $g_{00} = 0$, having $\frac{\partial r}{\partial u} = \frac{\partial r}{\partial v} = 0$ or $\frac{\partial r}{\partial u} g_{11} + 2 \frac{\partial t}{\partial u} g_{01} = \frac{\partial r}{\partial v} g_{11} + 2 \frac{\partial t}{\partial v} g_{01} = 0$. For a class in which $g_{00}, g_{11}, g_{22}, g_{01} \neq 0$, can be transformed into the DN form.

It is further proved that the existence of DN form depends on two coefficients g_{02} and g_{12} . A class of $(3 + 1)$ -dimensional space-times in which coefficients g_{02} or g_{12} are non-zero, cannot be transformed to the DN form. It will be interesting to adopt the procedure used in section 2, to obtain the DN form for different classes of $(3 + 1)$ -dimension space-times.

$$\frac{\partial u}{\partial v} \quad \frac{\partial u}{\partial u} \quad \frac{\partial u}{\partial v} \quad \frac{\partial v}{\partial u} \quad \frac{\partial v}{\partial v}$$

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